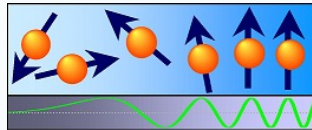


Experimental Physics EP2a

Thermodynamics & Electricity

– Magnetic field – Isolated charges, conductors



<https://bloch.physgeo.uni-leipzig.de/amr/>

Some history

1269 Pierre Pelerin de Maricourt

1600 William Gilbert

1802 Gian Domenico Romagnosi

1819 Hans Christian Ørsted

1820, 11 September

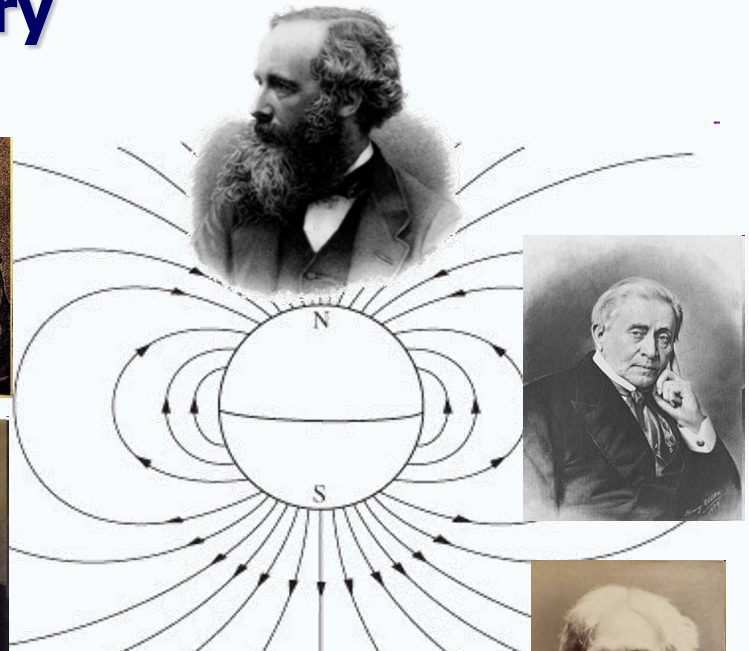
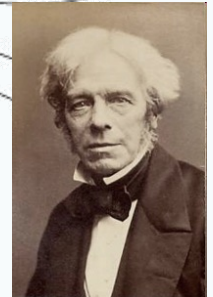
André-Marie Ampère

1820s Michael Faraday

Joseph Henry

1865 James Maxwell

A Dynamical Theory of the Electromagnetic Field



Experimental observations



The magnitude of the magnetic force on a moving charge is proportional to its speed $|v|$ and to its charge q .

The magnitude and the direction of this force depends on the magnitude $|B|$ and the direction of the magnetic field.

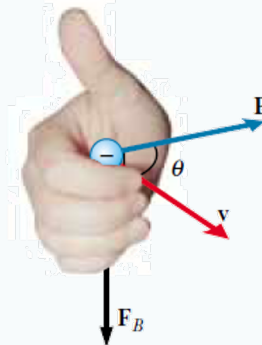
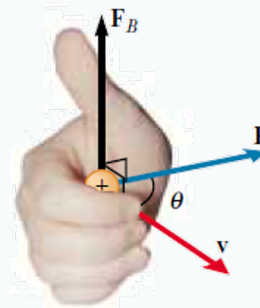
When a charged particle moves parallel to the magnetic field lines, the force F exerted upon the particle is zero.

However, if the angle between the magnetic field and the particle velocity is not zero, the force is perpendicular to both v and B .

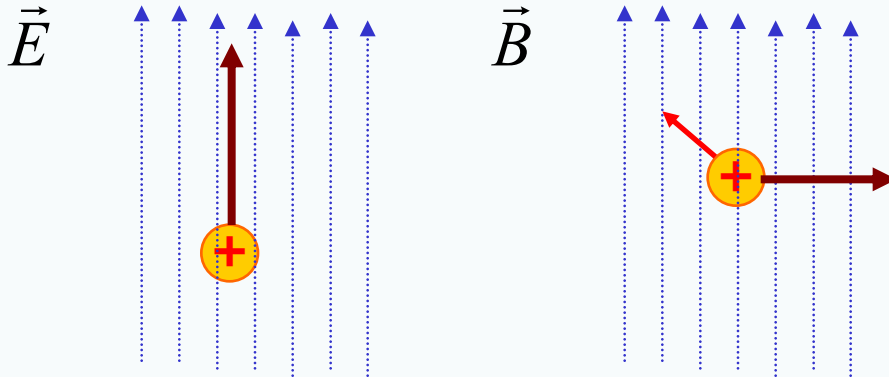
The magnitude of the magnetic forces will be proportional to $\sin(\theta)$, where θ is the angle between the directions of v and B .

If two charged particles with opposite charges move parallel to each other, the forces exerted upon the particles will be in opposite directions.

$$\vec{F}_B = q\vec{v} \times \vec{B}$$



How to probe magnetic field



$$W_E = \int \vec{F} d\vec{s}$$

$$W_B = 0 \quad \vec{F} \perp \frac{d\vec{s}}{dt}$$

$$\vec{F}_B = q\vec{v} \times \vec{B} \quad 1 \text{ T} = 10^4 \text{ G}$$

$$[B] = \frac{\text{N}}{\text{C} \cdot \frac{\text{m}}{\text{s}}} = \frac{\text{N}}{\text{Am}} \equiv \text{T}$$

$$\vec{a} \times (\vec{b} \times \vec{c}) = \vec{b}(\vec{a} \cdot \vec{c}) - \vec{c}(\vec{a} \cdot \vec{b})$$

$$\vec{B} = \frac{\vec{F} \times \vec{v}_\perp}{qv_\perp^2}$$

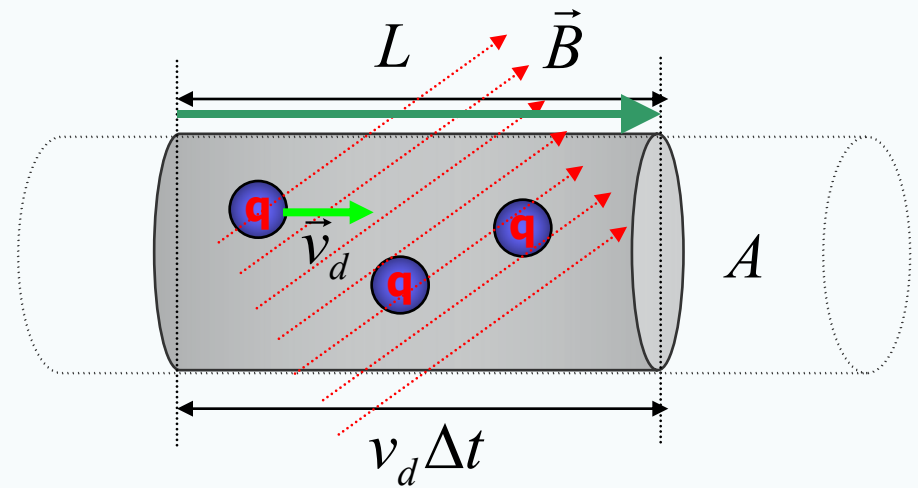
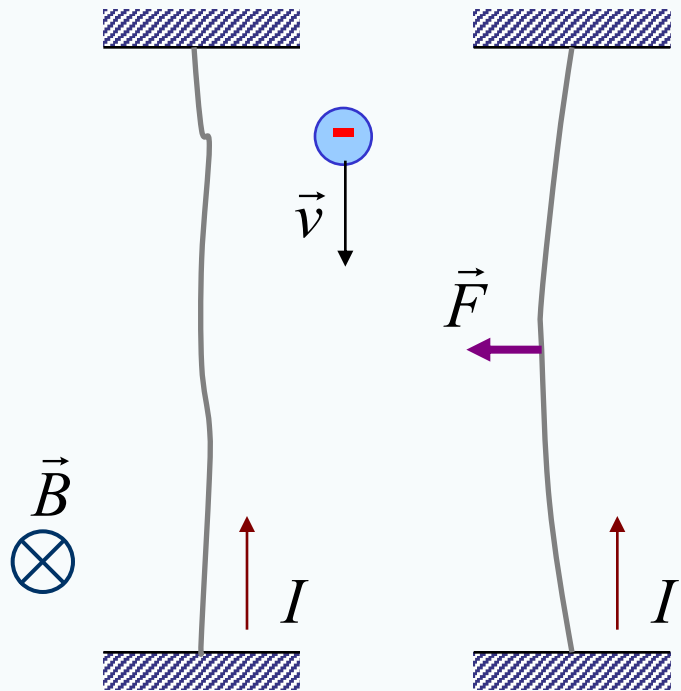
Magnetic field can alter only the direction of a charged particle moving in this field, but not the speed or kinetic energy of the particle.

TABLE 29.1 Some Approximate Magnetic Field Magnitudes

Source of Field	Field Magnitude (T)
Strong superconducting laboratory magnet	30
Strong conventional laboratory magnet	2
Medical MRI unit	1.5
Bar magnet	10^{-2}
Surface of the Sun	10^{-2}
Surface of the Earth	0.5×10^{-4}
Inside human brain (due to nerve impulses)	10^{-13}



Conductors

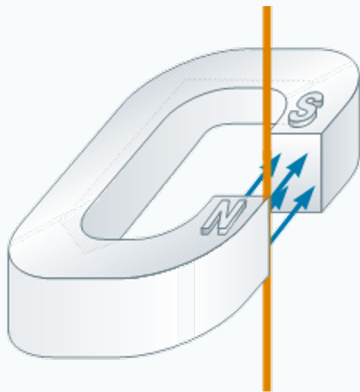


$$\vec{F}_B = Q\vec{v}_d \times \vec{B}$$

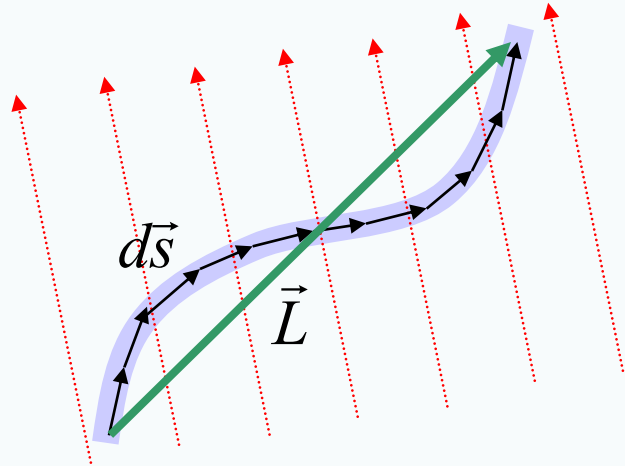
$$\vec{F}_B = nALq(\vec{v}_d \times \vec{B})$$

$$I = \frac{Q}{\Delta t} = \frac{Q}{L} v_d = nAq v_d$$

$$\vec{F}_B = I(\vec{L} \times \vec{B})$$



Arbitrarily shaped wires



$$d\vec{F}_B = I d\vec{s} \times \vec{B}$$

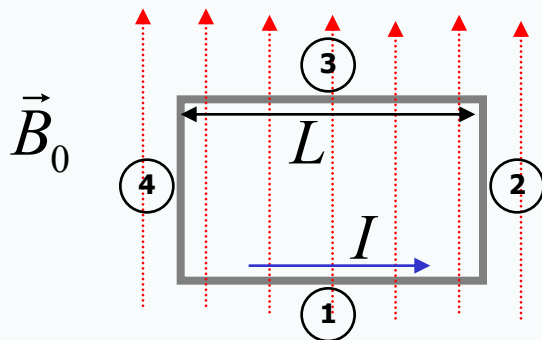
$$\vec{F}_B = I(\vec{L} \times \vec{B})$$

$$\vec{F}_B = I \int_a^b d\vec{s} \times \vec{B}$$

$$\vec{B} = \vec{B}(\vec{s})$$

$$\vec{B} = \vec{B}_0$$

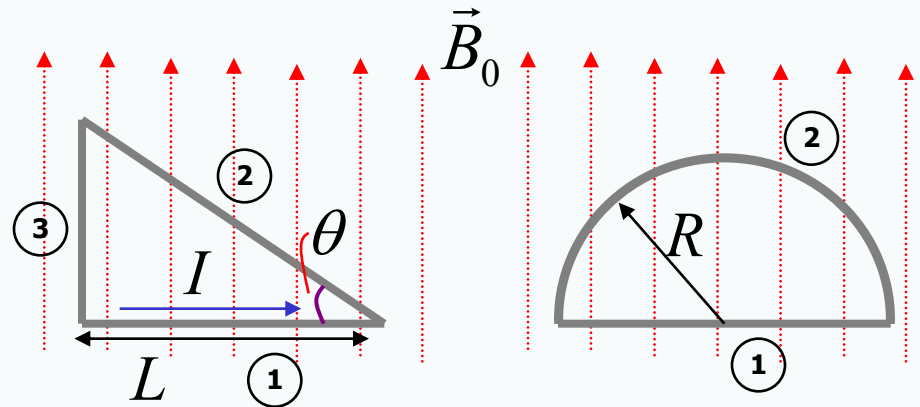
$$\vec{F}_B = I \left(\int_a^b d\vec{s} \right) \times \vec{B}_0 = I\vec{L} \times \vec{B}_0$$



$$\vec{F}_2 = \vec{F}_4 = 0$$

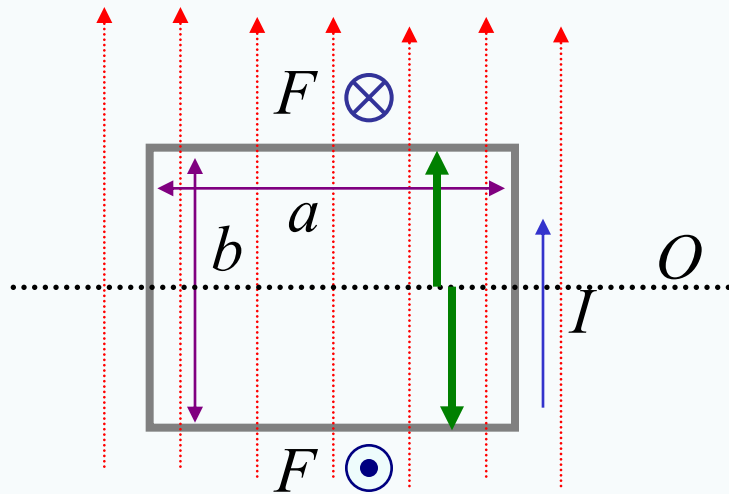
$$\vec{F}_1 = ILB_0 = -\vec{F}_3$$

$$\sum_{loop} \vec{F}_i = 0$$



Maximal torque on a loop

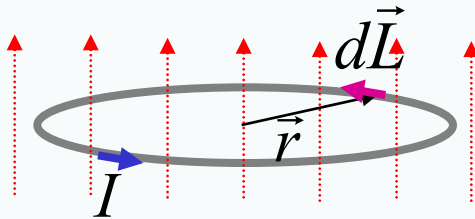
$$F = IabB_0$$



$$\vec{\tau} = \frac{d\vec{L}}{dt} = \frac{d(\vec{r} \times \vec{p})}{dt} = \vec{r} \times \vec{F}$$

$$\tau_{net} = \frac{1}{2} bF + \frac{1}{2} bF = IabB_0 = IAB_0$$

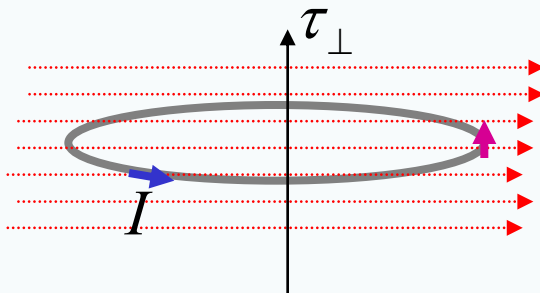
$$\vec{F}_B = I(\vec{L} \times \vec{B}) \quad \vec{a} \times (\vec{b} \times \vec{c}) = \vec{b}(\vec{a} \cdot \vec{c}) - \vec{c}(\vec{a} \cdot \vec{b})$$



$$\vec{\tau} = I[\vec{L}(\vec{r} \cdot \vec{B}) - \vec{B}(\vec{r} \cdot \vec{L})]$$

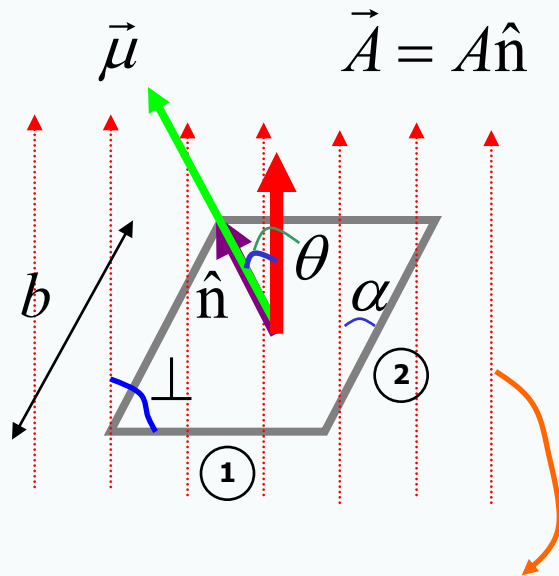
$$d\vec{\tau} = I[d\vec{L}(\vec{r} \cdot \vec{B}) - \vec{B}(\vec{r} \cdot d\vec{L})]$$

$$d\vec{\tau} = I[d\vec{L}(\vec{r} \cdot \vec{B}) - \vec{B}(\vec{r} \cdot d\vec{L})]$$



$$d\tau_{\perp} = IBR \int \cos \alpha dL_{\perp} = IBR^2 \int_0^{2\pi} \cos^2 \alpha d\alpha = IB\pi R^2$$

Torque – generalized equation



$$\tau_{net} = bF \cos \alpha$$

$$F = IaB$$

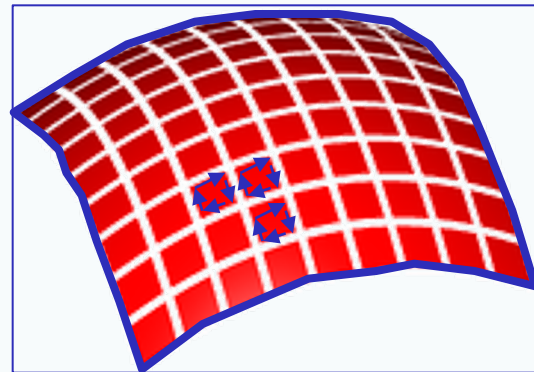
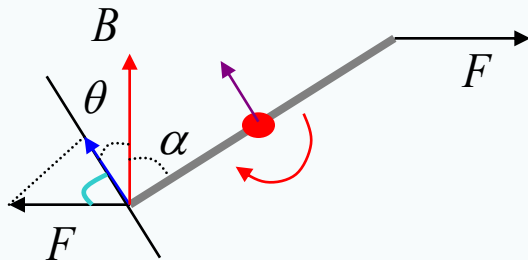
$$\tau_{net} = bF \sin \theta$$

$$\vec{\tau} = I\vec{A} \times \vec{B}$$

The direction of the normal to the surface is determined using right-hand rule by curling the fingers in the direction of the electric current.

$$\vec{\mu} = I\vec{A}$$

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$



$$\vec{\tau} = \int d\vec{\mu} \times \vec{B}$$

$$d\vec{\mu} = Id\vec{A}$$

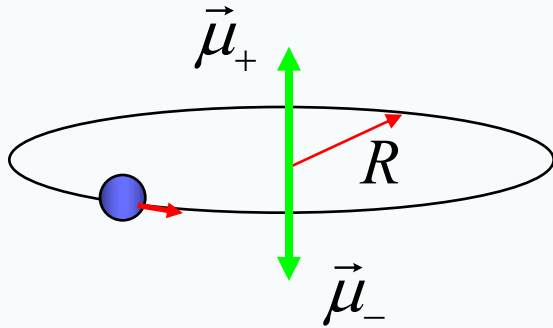
$$\vec{A} = \int d\vec{A}$$

$$dW_B = \tau d\theta = \tau_0 \sin \theta d\theta$$

$$dW_B = -dU$$

$$U = -\mu B \cos \theta = -\vec{\mu} \cdot \vec{B}$$

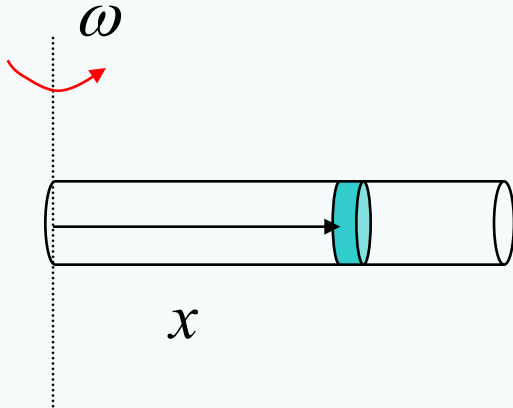
Magnetic moments



$$\vec{\mu} = I\vec{A} \quad \vec{\mu} = \frac{q}{T} \pi R^2 \hat{n} = \frac{1}{2} q \omega R^2 \hat{n}$$

$$\vec{L} = \omega \vec{I} = m \omega R^2 \hat{n} \quad \vec{\mu} = \frac{1}{2} \frac{q}{m} \vec{L}$$

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

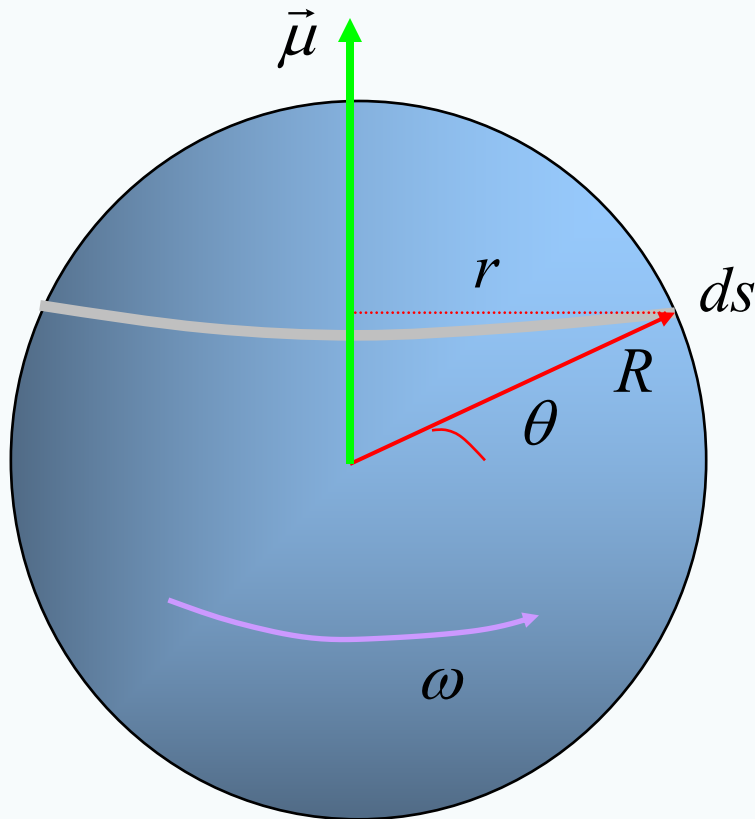


$$dI = \frac{\pi r^2 dx \rho \omega}{2\pi} \quad A = \pi x^2$$

$$\mu = \frac{\pi r^2 \rho \omega}{2} \int_0^L x^2 dx = \frac{Q \omega L^2}{6}$$

$$I = \int_0^L x^2 dm = \rho \pi r^2 \int_0^L x^2 dx = \frac{1}{3} M L^2 \quad \vec{\mu} = \frac{1}{2} \frac{Q}{M} \vec{L}$$

Magnetic moment of a spherical shell



$$d\mu = AdI \quad dI = \frac{dQ}{T}$$

$$dQ = \sigma \cdot 2\pi r ds$$

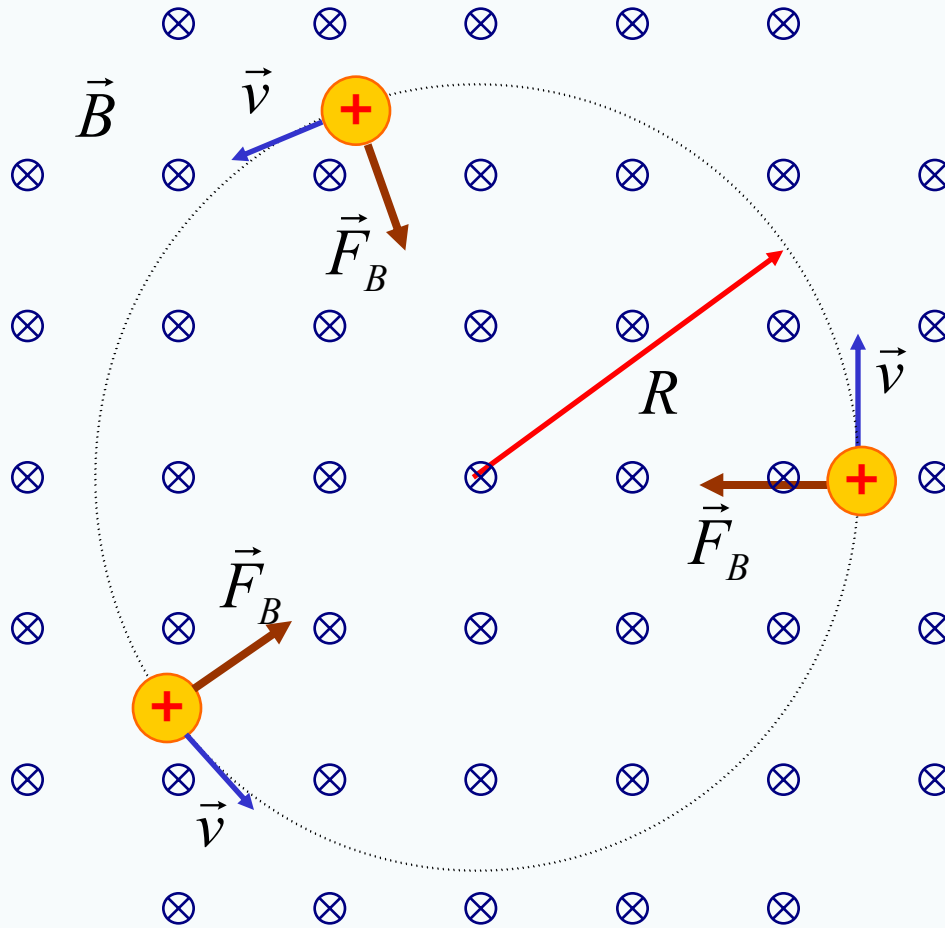
$$dQ = \sigma \cdot 2\pi R \cos \theta \cdot R d\theta$$

$$dI = \sigma \omega R \cos \theta \cdot R d\theta$$

$$d\mu = \pi R^4 \cos^3 \theta \cdot \sigma \omega d\theta$$

$$\mu = 2\pi\sigma\omega R^4 \int_0^{\pi/2} \cos^3 \theta d\theta = \frac{4}{3} \pi\sigma\omega R^4 = \frac{1}{3} Q\omega R^2$$

Charge moving perpendicular to \vec{B}



$$\omega = \frac{qB}{m}$$

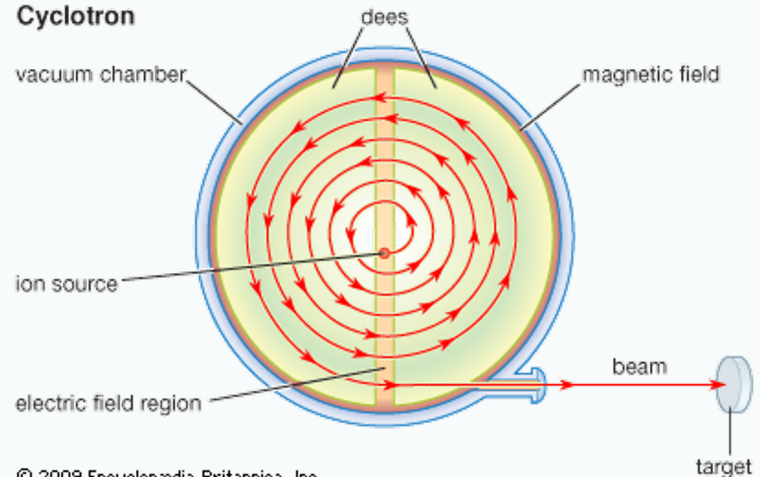
Cyclotron frequency

$$\sum \vec{F} = m\vec{a}$$

$$F_B = qvB = ma_{\perp}$$

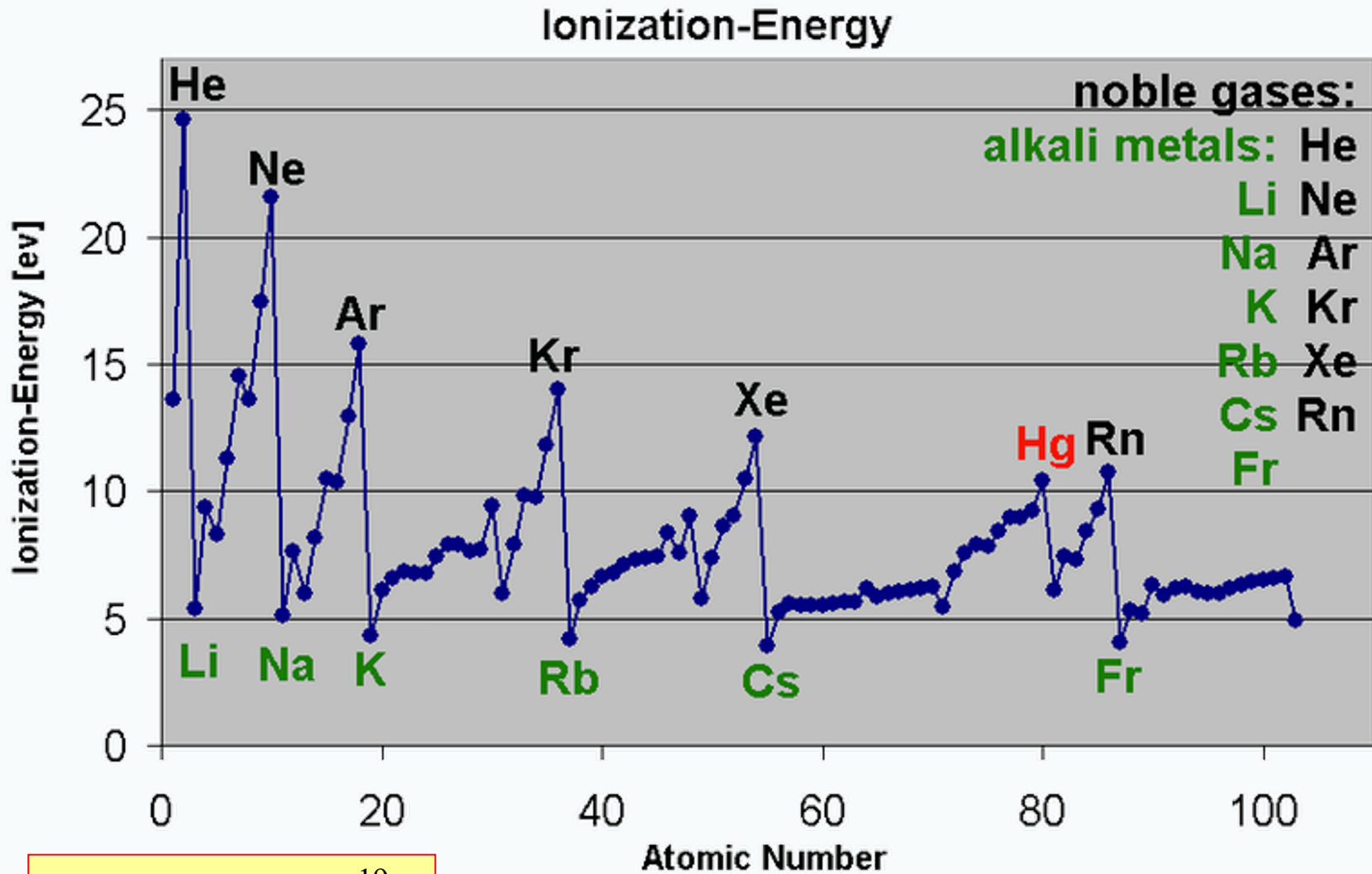
$$R = \frac{mv}{qB}$$

Cyclotron



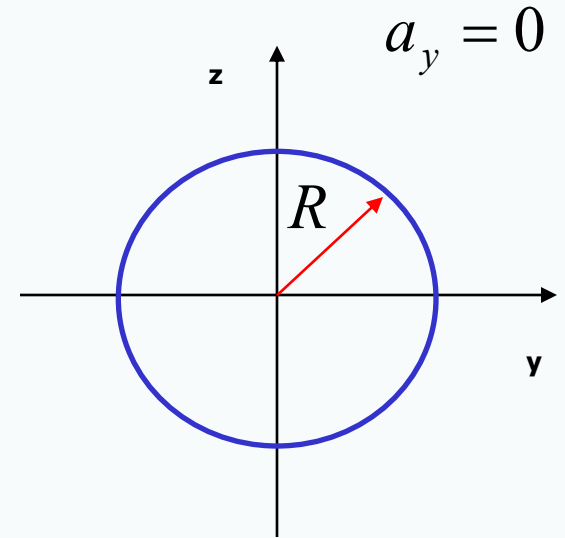
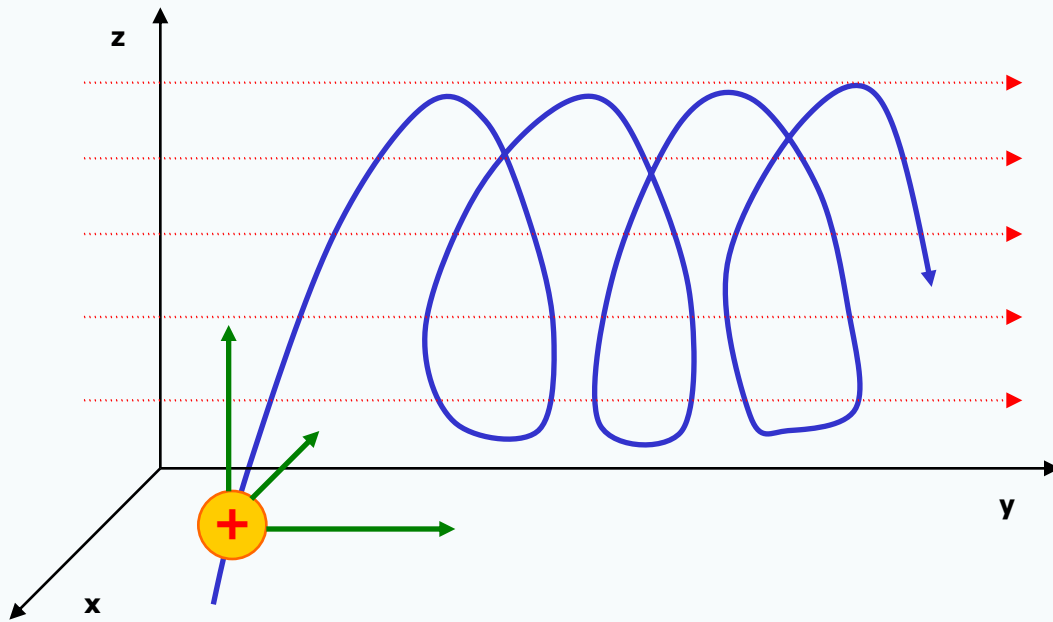
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Ionization energies

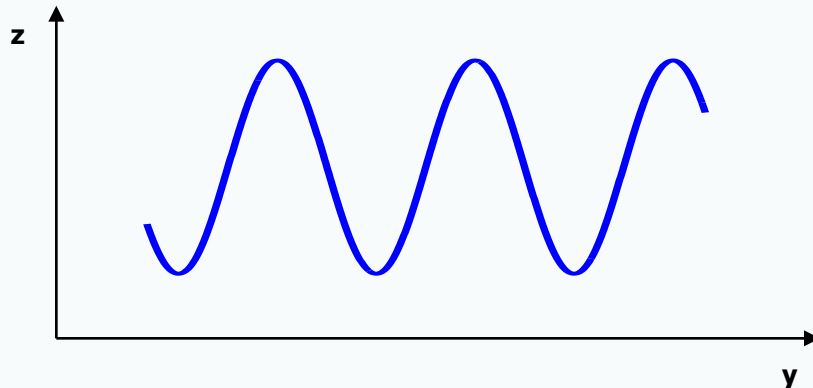


$1 \text{ eV} \approx 1.6 \times 10^{-19} \text{ J}$

Arbitrary angle

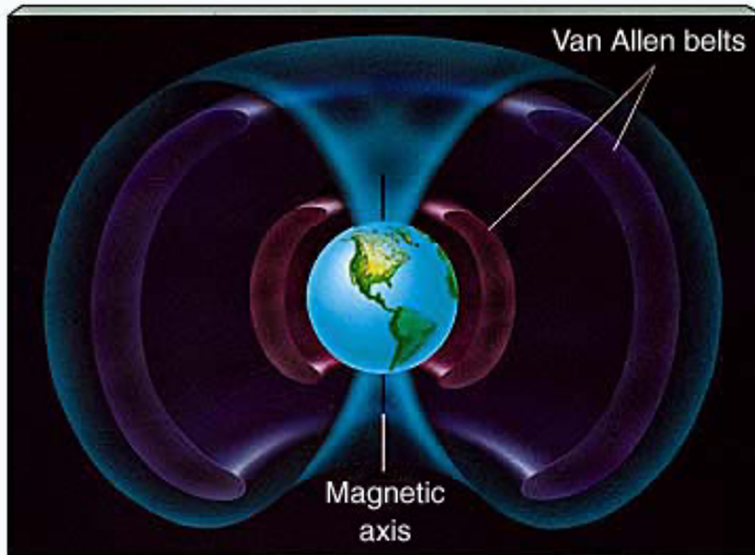
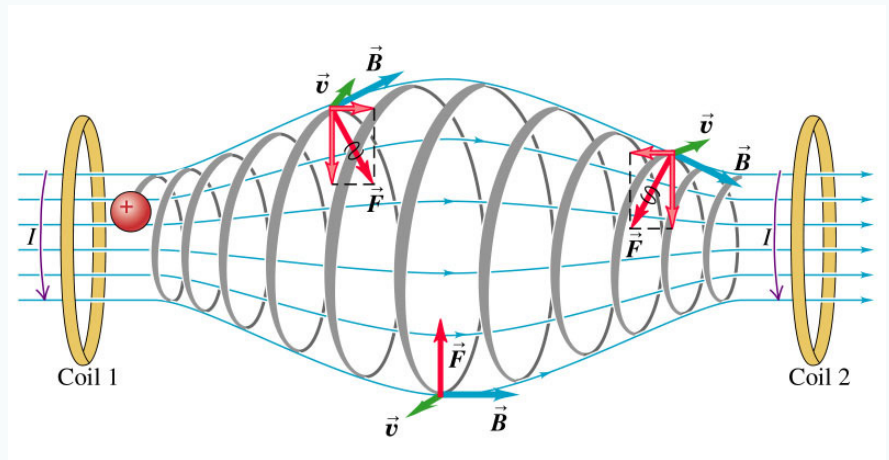
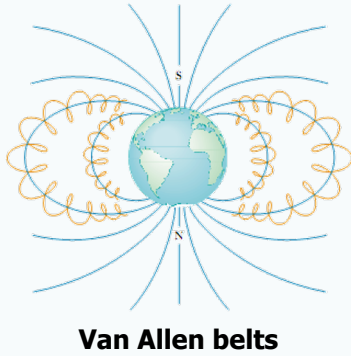
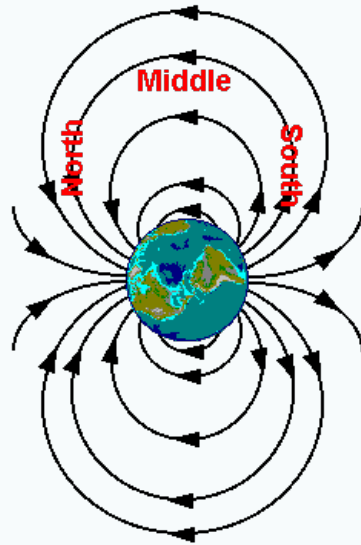
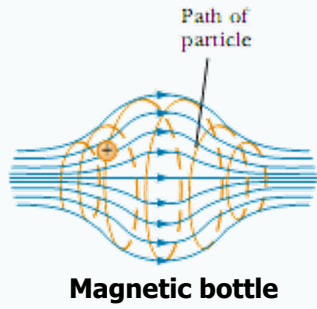


$$R = \frac{m|v_{zx}|}{qB} = \frac{m}{qB} \sqrt{v_x^2 + v_z^2}$$

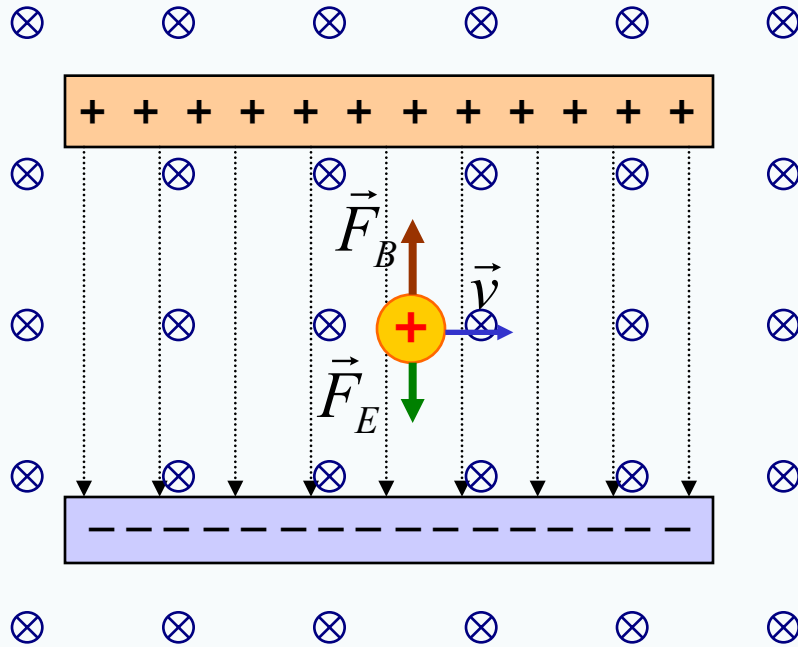


$$\begin{cases} v_y = \text{const} \\ v_x = v_0 \cos \alpha \\ v_z = v_0 \sin \alpha \end{cases} \quad \begin{cases} y = v_y t \\ x = v_0 t \cos y \\ z = v_0 t \sin y \end{cases}$$

Some examples



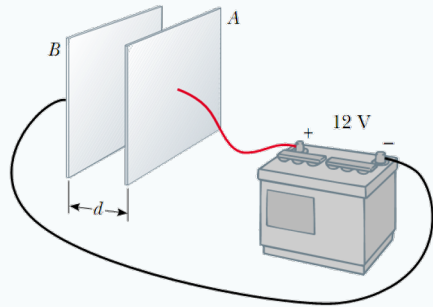
Velocity selector



$$\vec{F}_{net} = q\vec{v} \times \vec{B} + q\vec{E}$$

$$0 = qvB - qE$$

$$v_{unaffected} = \frac{E}{B}$$



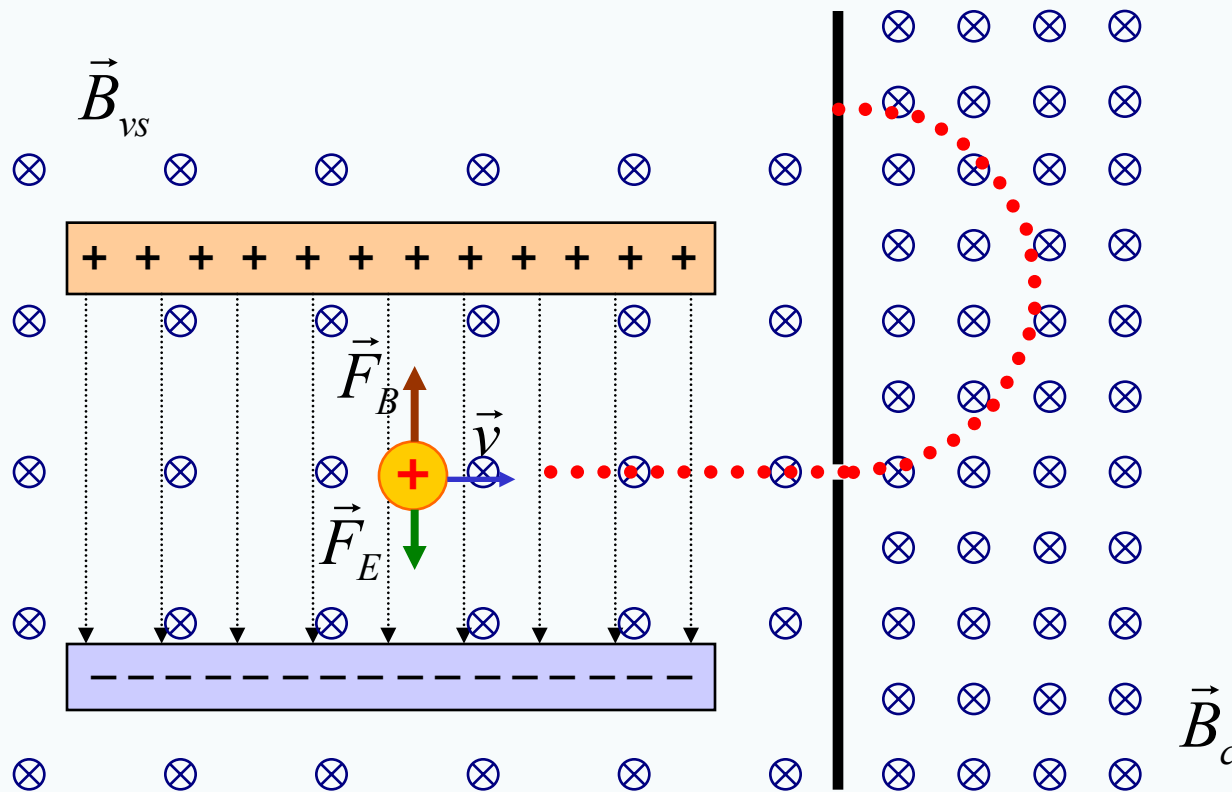
$$d = 1 \text{ mm} - 1 \text{ m}$$

$$B = 12 \text{ T}$$

$$v_{unaffected} = \frac{V}{dB}$$

$$v_{unaffected} = 1 \text{ km/s} - 1 \text{ m/s}$$

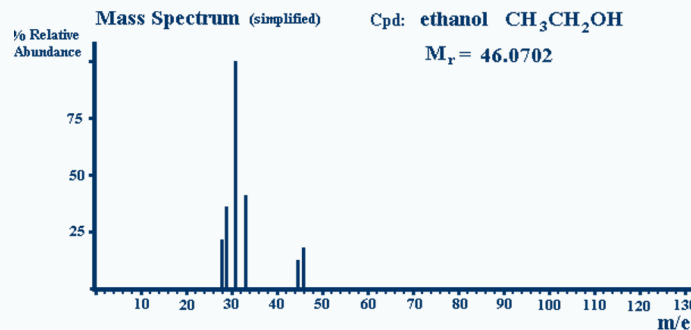
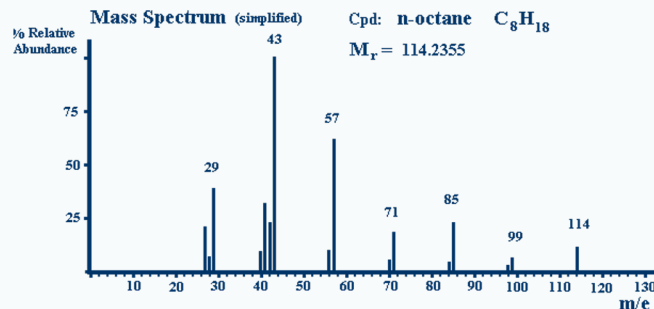
Mass spectrometer



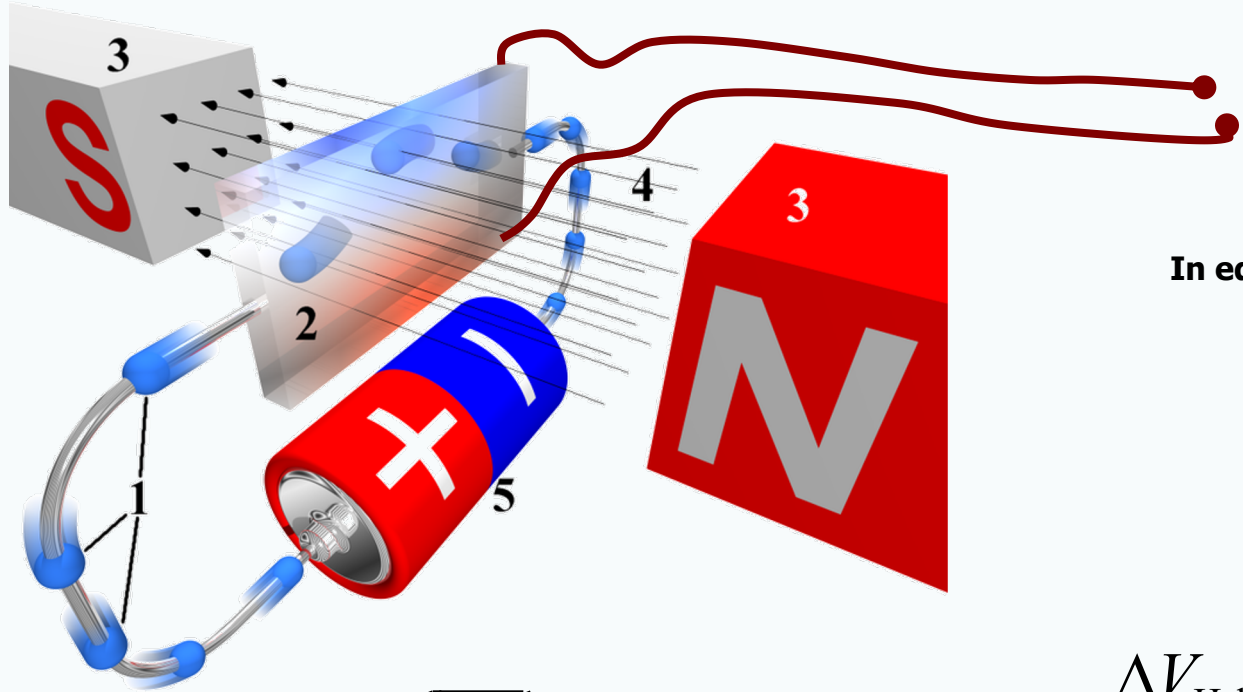
$$R = \frac{mv}{qB_c}$$

$$m = \frac{qB_c L}{2v}$$

$$m = \frac{qB_{vs} B_c L}{2E}$$



Hall effect



Hall voltage

In equilibrium:

$$qv_d B = qE_{\text{Hall}}$$

$$E_{\text{Hall}} = v_d B$$

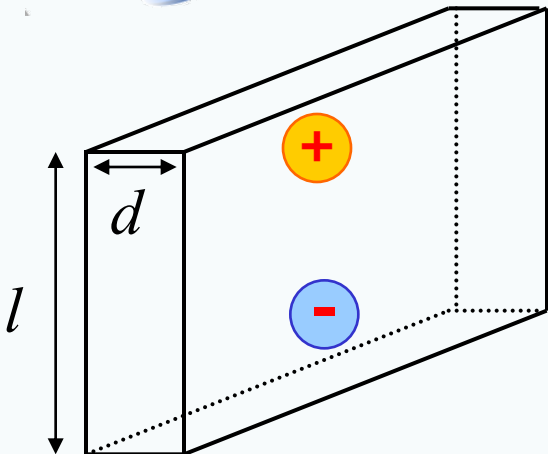
$$\Delta V_{\text{Hall}} = l \cdot E_{\text{Hall}} = l v_d B$$

$$I = nq v_d d l$$

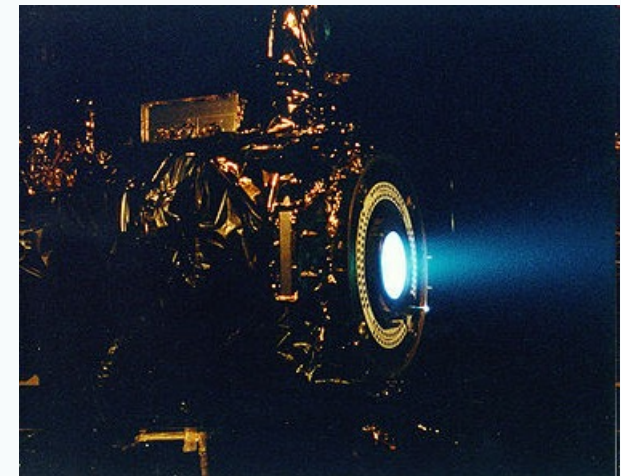
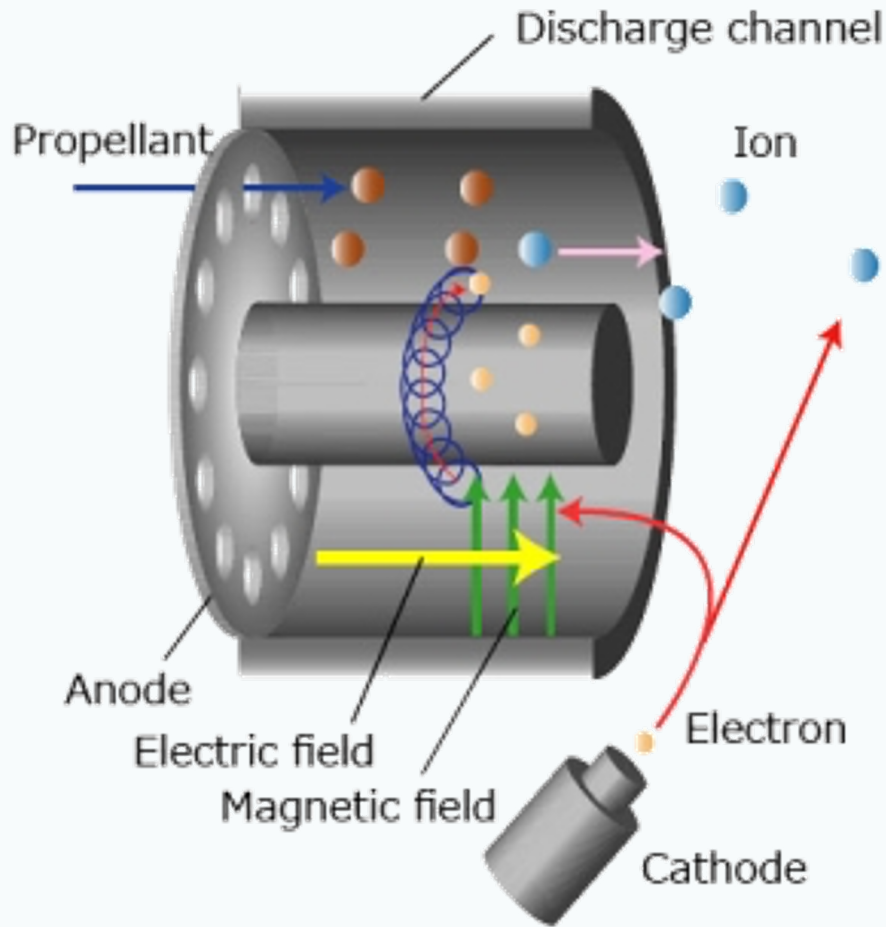
$$\Delta V_{\text{Hall}} = \frac{I}{nq d} B \equiv R_H \frac{IB}{d}$$

Silver: $R_H = 0.84 \times 10^{-10} \text{ m}^3/\text{C}$

Hall coefficient



Hall effect thruster



To remember!

- **Magnetic force acts only upon moving charges.**
- **Magnitude of magnetic field is measured in Tesla.**
- **The direction of this force perpendicular to both the velocity of the particles and to the magnetic field.**
- **The magnitude is proportional to the charge, the speed, the magnetic field and the sine of the angle between v and B .**
- **The same applies to unidirectional conductors, but with charge replaced by the electric current.**
- **For curved conductors, the total force is found by integrating along the conductor.**
- **No net magnetic force acts upon a closed-loop conductor placed in an uniform magnetic field.**



To remember!

- **Magnetic force acting upon a curved conducting wire carrying electric current is found by dividing it on small straight parts and summing up (integrating over) the forces acting upon them.**
- **Homogeneous magnetic field exert no force on any current loop.**
- **However, it can exert torque.**
- **The torque is maximal when the magnetic field is parallel to the plane of a flat current loop and zero it is perpendicular to it.**
- **Magnetic moment of a current loop is product of the electric current and the loop area.**
- **Any charged rotating object, i.e. having non-zero angular momentum, has as well magnetic moment.**



To remember!

- **If a charged particle enters magnetic field with initial velocity perpendicular to the field lines, it will get trapped by the magnetic field and perform circular motion.**
- **The angular frequency is called cyclotron frequency.**
- **For other angles the trajectory is a helix.**
- **Simultaneous application of electric and magnetic fields allows velocity selection of charged molecules.**
- **With one more magnetic field mass spectrometer can be constructed.**
- **In conductors carrying electric current and placed in magnetic field the Hall potential difference is developed due to deflection of moving electrons.**

